

Component-Interaction Automata

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ParaDiSe Seminar, Spring 2006

April 10, 2006

① Motivation

Introduction

Objectives

Specification languages

② Component-Interaction automata

CI automata language

Definition of the CI automaton

Composition of CI automata

③ Example

Simple system

④ Conclusion

Ongoing and future work

Introduction

Domain: Hierarchical component-based software systems

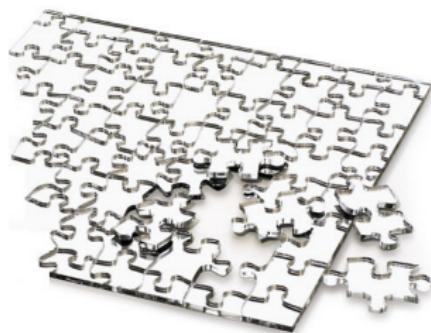
- Specification of interaction among components
 - Verification of interaction properties

Project:

- Verification of Component-Based Systems

ParaDiSe Laboratory, FI MU, Brno

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Jiří Sochor, Barbora Zimmerová,
Pavlína Vařeková, Nikola Beneš



Objectives – Verification

Issues of our interest

- Verification of coordination errors
 - Deadlock, computational progress, ...
 - Interaction between specific components
- Reconfiguration correctness
 - Component substitutability
 - Regression verification
- Component-interaction analysis
 - Removal of inactive components
 - Component placement in distributed environment

Objectives – Language

Language for specification of component interactions

- ① Flexible – respect various component models
 - Respect the architecture of a system
 - Single/multiple bindings on interfaces
 - Synchronization strategies
- ② Capture important information
 - Components – participants of communication
 - Hierarchical structure
- ③ Be of a manageable complexity
 - To enable automated verification

Specification languages – Overview

Architecture description languages – languages that have been defined within frameworks of architecture description languages

- Tracta
- Wright
- SOFA Behavior protocols

Automata based languages – languages for specification of component interactions that have been defined independently

- I/O automata
- Team automata
- Interface automata

CI automata language

Component-Interaction automata language

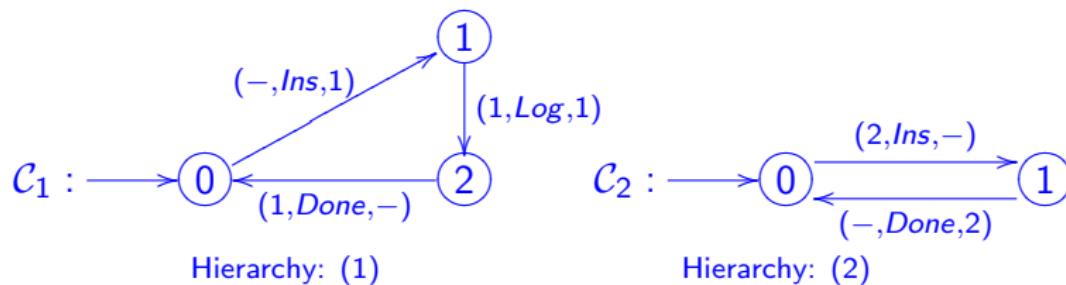
(CI automata for short)

- Automata-based language
finite state model, infinite executions/traces
- Three types of actions (*input*, *output* and *internal*)
general used concept
- CCS like synchronization
one input and one output action which becomes internal later on
- Flexible composition
can be parametrized by characteristics of a system
- Preservation of important interaction information
participants of communication, hierarchy

Definition of the CI automaton

Component-Interaction automaton $\mathcal{C} = (Q, Act, \delta, I, H)$

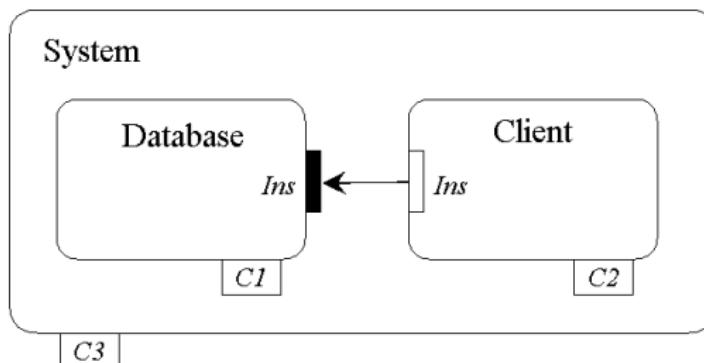
- States, Initial states
- Actions
- Labeled transitions (structured labels - components, actions)
 - input, output and internal
- Hierarchy



Composition of CI automata

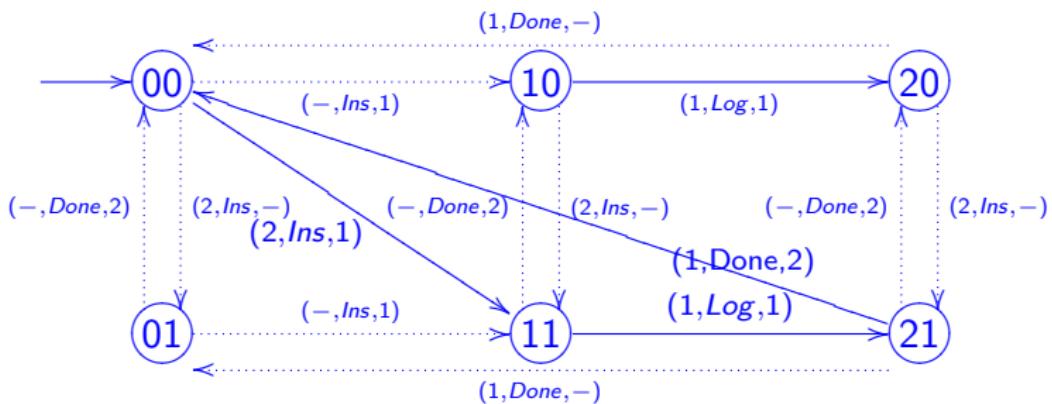
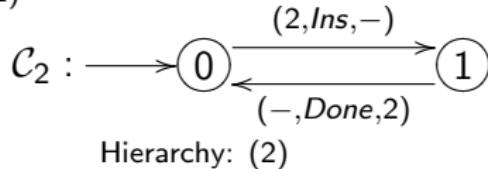
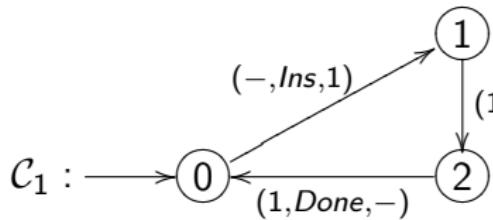
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- ① Set \mathcal{S} of CI automata to be composed
- ② All possible interactions – product automaton with transition set given as a **complete transition space $\Delta_{\mathcal{S}}$**
- ③ Feasible interactions – transition set $\delta \subseteq \Delta_{\mathcal{S}}$
- ④ Composite automaton $\otimes_T \mathcal{S}$ where $\delta = \Delta_{\mathcal{S}} \setminus T$



Composition of CI automata

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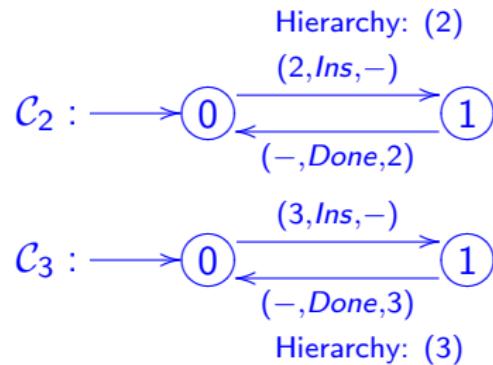
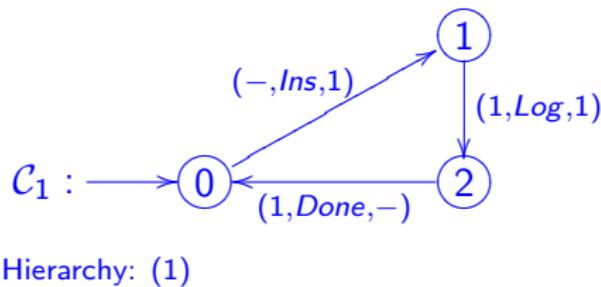
In figures, states ij stand for (i, j)

Example – Simple system

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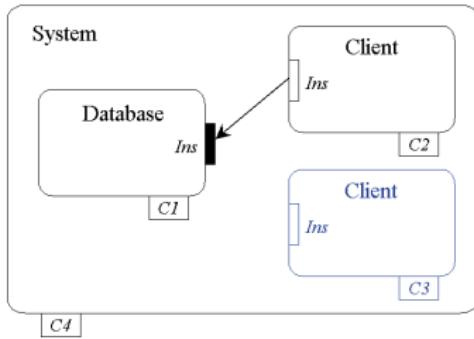
Simple system

- Consist of three components – database \mathcal{C}_1 , and clients $\mathcal{C}_2, \mathcal{C}_3$
- Respect architectural description
- Use one-to-one handshake synchronization



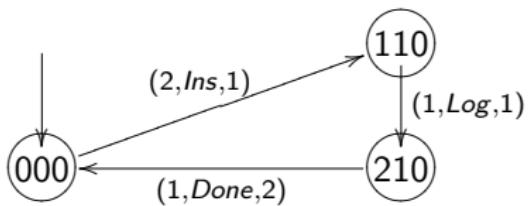
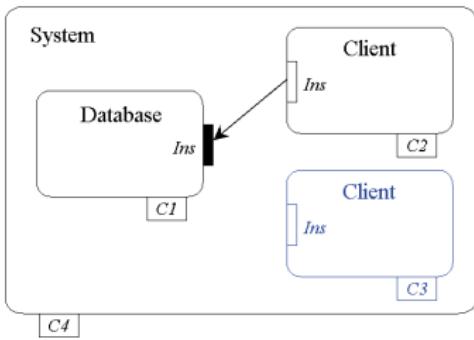
Example – Simple system

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Example – Simple system

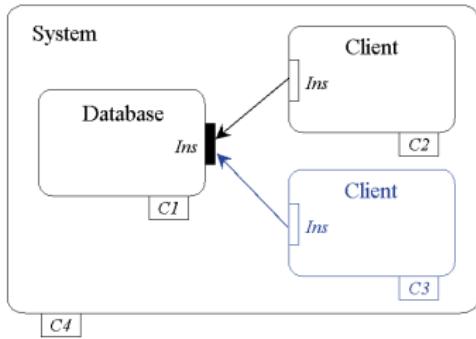
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Hierarchy: $((1),(2),(3))$

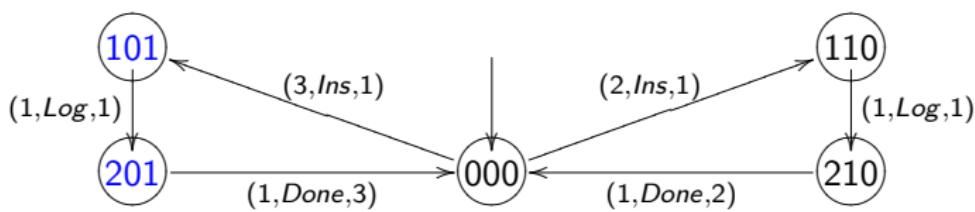
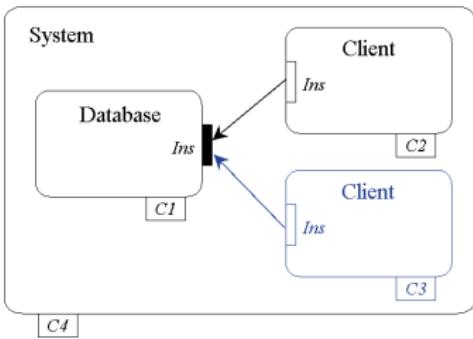
Example – Simple system

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Example – Simple system

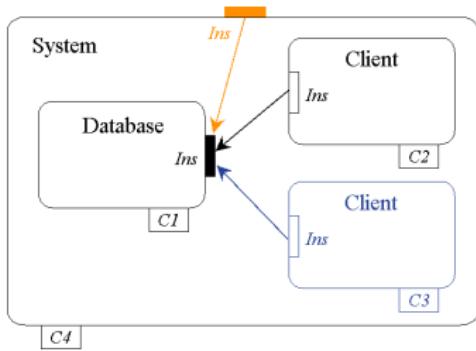
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Hierarchy: $((1),(2),(3))$

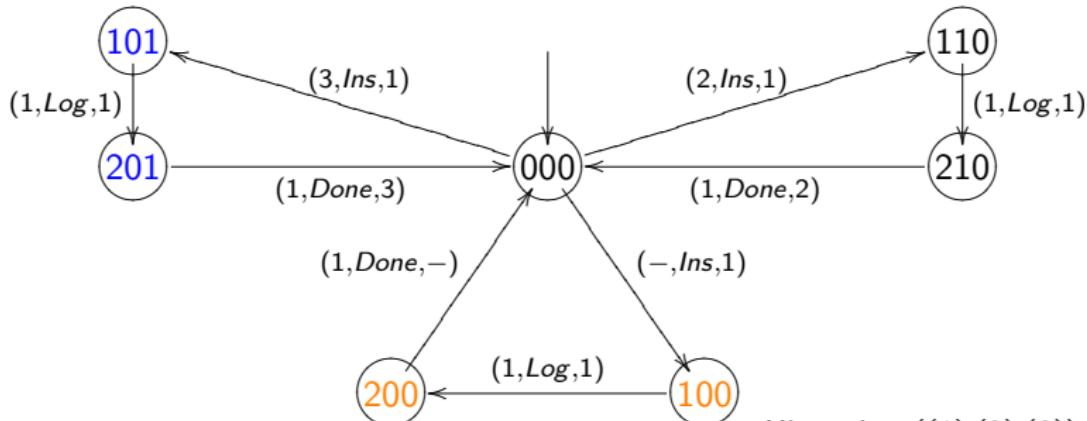
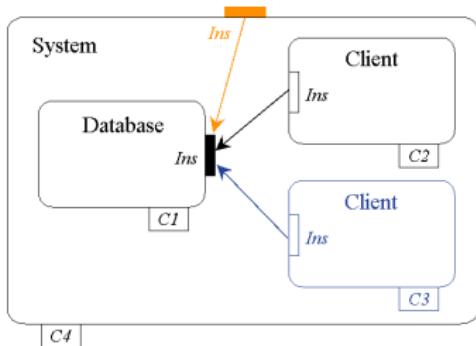
Example – Simple system

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Example – Simple system

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Hierarchy: ((1),(2),(3))

Ongoing and future work

Ongoing work

- Composition operator (and others)
- Behavioural equivalencies
- Temporal logic
- CI automata → DiVinE input language

Future work

- Verification of coordination errors
- Reconfiguration correctness
- Component-interaction analysis

Thank you

Thank you for your attention

